

## Problem #1)

(1) Let

$$x = \frac{1}{\sqrt{2}\omega} (a + a^\dagger), \quad p = i\sqrt{\frac{\omega}{2}} (a - a^\dagger)$$

The inverse is

$$a = \frac{\omega x + ip}{\sqrt{2}\omega}, \quad a^\dagger = \frac{\omega x - ip}{\sqrt{2}\omega}$$

And so  $[x, p] = i \Rightarrow$ 

$$\begin{aligned} [a, a^\dagger] &= \frac{[\omega x + ip, \omega x - ip]}{2\omega} = \frac{-i\cancel{\omega}[x, p] + i\cancel{\omega}[p, x]}{2\cancel{\omega}} \\ &= \frac{-i \cdot i + i \cdot (-i)}{2} = 1 \end{aligned}$$

And furthermore

$$\begin{aligned} H &= \frac{1}{2} p^2 + \frac{1}{2} \omega^2 x^2 \\ &= \frac{1}{2} \frac{\omega}{2} (a - a^\dagger)^2 + \frac{1}{2} \omega^2 \frac{1}{2\omega} (a + a^\dagger)^2 \\ &= \frac{\omega}{4} (aa^\dagger + a^\dagger a + a^\dagger a^\dagger + a a a) \\ &= \frac{\omega}{2} (a^\dagger a + a a^\dagger) \\ &= \omega (a^\dagger a + \frac{1}{2}) \end{aligned}$$

Now to get the Heisenberg operators, use

$$[a, H] = \omega[a, a^\dagger a] = \omega[a, a^\dagger]a = \omega a, \quad [a^\dagger, H] = -\omega a^\dagger$$

$$\text{So } a_H(t) = e^{iHt} a e^{-iHt} \quad \therefore \frac{\partial}{\partial t} a_H(t) = i e^{iHt} [H, a] e^{-iHt} = -i\omega a_H(t)$$

$$a_H(t=0) = a \quad \therefore \boxed{a_H(t) = a e^{-i\omega t}}$$

$$\text{Likewise } \frac{\partial}{\partial t} a_H^\dagger(t) = i e^{iHt} [H, a^\dagger] e^{-iHt} = i\omega a_H^\dagger(t) \quad \therefore \boxed{a_H^\dagger(t) = a^\dagger e^{i\omega t}}$$

Putting this all together

$$\begin{aligned}
 X(t) &= \frac{1}{\sqrt{2}\omega} (ae^{-i\omega t} + ae^{i\omega t}) \\
 P(t) &= -i\sqrt{\frac{\omega}{2}} (ae^{-i\omega t} - ae^{i\omega t})
 \end{aligned}$$

$$\begin{aligned}
 \underline{(2)} \quad D(t_1, -t_2) &= \langle 0 | X(t_1) X(t_2) | 0 \rangle \\
 &= \frac{1}{2\omega} \langle 0 | (ae^{-i\omega t_1} + ae^{i\omega t_1}) (ae^{-i\omega t_2} + ae^{i\omega t_2}) | 0 \rangle \\
 &= \frac{1}{2\omega} e^{i\omega(t_2 - t_1)} \langle 0 | a a^\dagger | 0 \rangle
 \end{aligned}$$

$$D(t_1, -t_2) = \frac{e^{i\omega(t_1 - t_2)}}{2\omega}$$

$$\begin{aligned}
 (\partial_t^2 + \omega^2) D(t) &= (\partial_t^2 + \omega^2) \frac{e^{-i\omega t}}{2\omega} \\
 &= \left( \frac{(-i\omega)^2 + \omega^2}{2\omega} \right) e^{-i\omega t} = 0 \quad \checkmark
 \end{aligned}$$

$$\begin{aligned}
 \underline{(3)} \quad \text{If } t_1 \geq t_2: \quad D_F(t_1, -t_2) &= \langle 0 | T X(t_1) X(t_2) | 0 \rangle \\
 &= \langle 0 | X(t_1) X(t_2) | 0 \rangle = D_F(t_1, -t_2) = \frac{e^{-i\omega(t_1 - t_2)}}{2\omega} \\
 \text{If } t_2 \geq t_1: \quad D_F(t_1, -t_2) &= \langle 0 | X(t_2) X(t_1) | 0 \rangle = D_F(t_2, -t_1) \\
 &= \frac{e^{-i\omega(t_2 - t_1)}}{2\omega}
 \end{aligned}$$

Combining these:

$$D_F(t_1, -t_2) = \frac{e^{-i\omega|t_1 - t_2|}}{2\omega}$$

(4) (a)

When  $t_1 \neq t_2$ , we know this vanishes from (2),

so the case of interest is  $t_1 = t_2$ .

As  $t_1 = t_2 + \epsilon$ ,  $\epsilon > 0$

$$\partial_{t_1} \langle 0 | T X(t_1) X(t_2) | 0 \rangle = \frac{1}{2\omega} \partial_{t_1} e^{-i\omega(t_1-t_2)} = -\frac{i}{2} + O(\epsilon)$$

As  $\epsilon < 0$

$$\partial_{t_1} \langle 0 | T X(t_1) X(t_2) | 0 \rangle = \frac{i}{2\omega} \partial_{t_1} e^{+i\omega(t_1-t_2)} = +\frac{i}{2} + O(\epsilon)$$

By the definition of the derivative

$$\begin{aligned} 0(\epsilon) + i &= \partial_{t_1} \langle 0 | T X(t_2 + \epsilon) X(t_2) | 0 \rangle - \partial_{t_1} \langle 0 | T X(t_2 - \epsilon) X(t_2) | 0 \rangle \\ &= \int_{t_2 - \epsilon}^{t_2 + \epsilon} dt_1 \partial_{t_1}^2 \langle 0 | T X(t_1) X(t_2) | 0 \rangle \end{aligned}$$

For all  $\epsilon > 0$ .

Taking  $\lim_{\epsilon \rightarrow 0}$  we get

$$\partial_{t_1}^2 \langle 0 | T X(t_1) X(t_2) | 0 \rangle = -i \delta(t_1 - t_2) + \text{finite}$$

Using (2) we can find the finite contribution, so

$$\boxed{(\partial_{t_1}^2 + \omega^2) \langle 0 | T X(t_1) X(t_2) | 0 \rangle = -i \delta(t_1 - t_2)}$$

Solution Set #5

(4) (b)

The Heisenberg EOMs are

$$\dot{x} = -i [x, H] = -i [x, \frac{p^2}{2}] = -\frac{i}{2} ([x, p] p + p [x, p]) = p$$

$$\dot{p} = -i [p, H] = -i [p, \frac{1}{2} \omega^2 x^2] = -\omega^2 x$$

$$\partial_\epsilon \langle 0 | T x(t_2 + \epsilon) x(t_2) | 0 \rangle = \partial_\epsilon \langle 0 | x(t_2 + \epsilon) x(t_2) | 0 \rangle$$

$$= \langle 0 | \dot{x}(t_2 + \epsilon) x(t_2) | 0 \rangle = \langle 0 | p(t_2 + \epsilon) x(t_2) | 0 \rangle$$

$$\partial_\epsilon \langle 0 | T x(t_2 - \epsilon) x(t_2) | 0 \rangle = \partial_\epsilon \langle 0 | x(t_2) x(t_2 - \epsilon) | 0 \rangle$$

$$= - \langle 0 | x(t_2) p(t_2 + \epsilon) | 0 \rangle$$

$$\int_{-\epsilon}^{\epsilon} \partial_{t_1}^2 \langle 0 | T x(t_1) x(t_2) | 0 \rangle dt_1 = \partial_\epsilon \langle 0 | T x(t_2 + \epsilon) x(t_2) | 0 \rangle$$

$$- \partial_\epsilon \langle 0 | T x(t_2 - \epsilon) x(t_2) | 0 \rangle$$

$$= \langle 0 | [p(t_2 + \epsilon), x(t_2)] | 0 \rangle = -i \delta(\epsilon) = -i \delta(t_2 - t_1)$$

Again, using (2) to see that finite terms vanish

$$\boxed{(\partial_{t_1}^2 + \omega^2) \langle 0 | T x(t_1) x(t_2) | 0 \rangle = -i \delta(t_1 - t_2)}$$

(5) It suffices to consider  $t_1 > t_2 > t_3 > t_4$

(because  $t_i$ 's can always be chosen this way and the answer is invariant under permutations of  $t_i$ 's.)

$$\begin{aligned}
 G_4 &= \langle 0 | T X(t_1) X(t_2) X(t_3) X(t_4) | 0 \rangle = \langle 0 | X(t_1) X(t_2) X(t_3) X(t_4) | 0 \rangle \\
 &= \frac{1}{4\omega^2} \langle 0 | a e^{-i\omega t_1} (a e^{-i\omega t_2} + a^\dagger e^{i\omega t_2}) (a e^{-i\omega t_3} + a^\dagger e^{i\omega t_3}) a^\dagger e^{i\omega t_4} | 0 \rangle \\
 &= \frac{1}{4\omega^2} e^{-i\omega(t_1+t_2-t_3-t_4)} \langle 0 | a a a^\dagger a^\dagger | 0 \rangle \\
 &\quad + \frac{1}{4\omega^2} e^{-i\omega(t_1-t_2+t_3-t_4)} \langle 0 | a a^\dagger a a^\dagger | 0 \rangle
 \end{aligned}$$

Now to evaluate the matrix elements

$$\langle 0 | a a a^\dagger a^\dagger | 0 \rangle = \langle 0 | a [a, a^\dagger a^\dagger] | 0 \rangle = 2 \langle 0 | a a^\dagger | 0 \rangle = 2$$

$$\langle 0 | a a^\dagger a a^\dagger | 0 \rangle = \langle 0 | a a^\dagger [a, a^\dagger] | 0 \rangle = \langle 0 | a a^\dagger | 0 \rangle = 1$$

$$G_4 = \frac{1}{4\omega^2} (2 e^{-i\omega(t_1+t_2-t_3-t_4)} + e^{-i\omega(t_1-t_2+t_3-t_4)})$$

$$D_F(t_1-t_2) D_F(t_3-t_4) + D_F(t_1-t_3) D_F(t_2-t_4) + D_F(t_1-t_4) D_F(t_2-t_3)$$

$$= \frac{1}{4\omega^2} (e^{-i\omega(t_1-t_2+t_3-t_4)} + e^{-i\omega(t_1-t_3+t_2-t_4)} + e^{-i\omega(t_1-t_4+t_2-t_3)})$$

$$= G_4$$

So these agree!

2.

$$a) a_I(t) = \exp[iE(a^\dagger a)t] a \exp[-iE(a^\dagger a)t]$$

$$\text{Now } e^{+iA} B e^{-iA} = B + i[A, B] + \frac{(i)^2}{2!} [A, [A, B]] + \dots$$

So  $\quad \quad \quad 0$  since  $a^2 = 0$ .

$$a_I(t) = a + iEt (a^\dagger a a - a a^\dagger a) + \dots$$

$$= a + iEt (-a(a a^\dagger + 1)) + \dots$$

$$= a - iEt a + \dots$$

$$= a + (-iEt) a + \frac{(-iEt)^2}{2!} a + \dots$$

$$= e^{-iEt} a.$$

$$a_I^\dagger(t) = (a_I(t))^\dagger = e^{+iEt} a^\dagger$$

$$\text{So } V_I(t) = V_0 (a_I(t) e^{i\omega t} + a_I^\dagger(t) e^{-i\omega t})$$

$$= V_0 (a e^{-i(E-\omega)t} + a^\dagger e^{i(E-\omega)t})$$

$$b) \langle 0(0) |_I T a_I(t_1) a_I^\dagger(t_2) | 0(0) \rangle_I = \theta(t_1 - t_2) \langle 0(0) |_I a a^\dagger | 0(0) \rangle_I e^{-iE(t_1 - t_2)}$$

$$+ \theta(t_2 - t_1) \langle 0(0) |_I a^\dagger a | 0(0) \rangle_I e^{iE(t_1 - t_2)}, \quad | 0(0) \rangle_I = | 0 \rangle.$$

$$\text{and } \langle 0 | a^\dagger a | 0 \rangle = 0 \quad \text{and } \langle 0 | a a^\dagger | 0 \rangle = 1.$$

$$= \boxed{\theta(t_1 - t_2) e^{-iE(t_1 - t_2)}}$$

$$c) \langle 1a \rangle_I | 0a \rangle_I = e^{-iEt} \langle 0 | a T \exp \left[ -i \int_0^T V_I(t') dt' \right] | 0 \rangle$$

$$= e^{-iEt} \langle 0 | a \left( 1 - i \int_0^t V_I(t') dt' + (-i)^2 \int_0^t dt' \int_0^{t'} V_I(t') V_I(t'') + \dots \right) | 0 \rangle$$

To first order in  $V_0$

we have

$$= e^{-iEt} \left( \langle 0 | a | 0 \rangle - i V_0 \left( \int_0^t dt' e^{-i(E-\omega)t'} \langle 0 | a | 0 \rangle + \int_0^t dt' e^{i(E-\omega)t'} \langle 0 | a | 0 \rangle \right) \right)$$

$$= e^{-iEt} \frac{-i V_0}{i(E-\omega)} \left( e^{i(E-\omega)t} - 1 \right) = e^{-iEt} \frac{V_0}{(E-\omega)} \left( e^{i(E-\omega)t} - 1 \right)$$

$$D) \langle 0a \rangle_I | 0a \rangle_I = \langle 0 | 1 | 0 \rangle - i \int_0^t \langle 0 | V_2 | 0 \rangle$$

$$- V_0^2 \int_0^t dt' \int_0^{t'} dt'' \langle 0 | a a^\dagger | 0 \rangle e^{-i(E-\omega)t'} e^{i(E-\omega)t''}$$

$$\text{Now } \int_0^t dt' \int_0^{t'} dt'' e^{-i(E-\omega)t'} e^{i(E-\omega)t''} = \frac{1}{i(E-\omega)} \int_0^t dt' e^{-i(E-\omega)t'} \left( e^{i(E-\omega)t'} - 1 \right)$$

$$= \frac{1 - e^{-i(E-\omega)t}}{(E-\omega)^2} + \frac{t}{i(E-\omega)}$$

So

$$\langle 0 | \psi(t) \rangle = 1 - \frac{V_0^2}{(E-w)^2} (1 - e^{-i(E-w)t}) - \frac{V_0^2 t}{2i(E-w)} = \langle 0 | \psi(t) \rangle$$

$$So \quad |c_0|^2 = 1 - \frac{V_0^2}{2(E-w)^2} (2 - e^{-i(E-w)t} - e^{i(E-w)t}) + O(V_0^4)$$

$$|c_1|^2 = \frac{V_0^2}{(E-w)^2} (2 - e^{i(E-w)t} - e^{-i(E-w)t})$$

$$So \quad |c_0|^2 + |c_1|^2 = 1 \quad \checkmark$$

e). Now

$$i \frac{d}{dt} |\psi_I(t)\rangle = V_I(t) |\psi_I(t)\rangle$$

$$So \quad i \frac{d}{dt} \begin{pmatrix} C_0^I(t) \\ C_1^I(t) \end{pmatrix} = \begin{bmatrix} 0 & V_0 e^{-i(E-w)t} \\ V_0 e^{+i(E-w)t} & 0 \end{bmatrix} \begin{pmatrix} C_0^I(t) \\ C_1^I(t) \end{pmatrix}$$

$$So \quad i \dot{C}_0^I(t) = V_0 e^{-i(E-w)t} C_1^I(t)$$

$$i \dot{C}_1^I(t) = V_0 e^{i(E-w)t} C_0^I(t)$$

$$So \quad i \ddot{C}_0^I(t) = -i V_0 (E-w) e^{-i(E-w)t} C_1^I(t) + V_0 e^{-i(E-w)t} (-i) i \dot{C}_1^I(t)$$

$$= -i V_0 (E-w) C_1^I(t) - i V_0^2 C_0^I(t)$$

$$So \quad \ddot{C}_0^I(t) + V_0^2 C_0^I(t) + (E-w) i \dot{C}_0^I(t) = 0$$



$$\text{Let } \Delta = E - w.$$

$$\ddot{C}_0 + V_0^2 C_0 + \Delta i \dot{C}_0 = 0.$$

Linear 2nd order differential equation.

so  $C_0 \sim e^{imt}$ : Plugging in gives

$$(m^2 - V_0^2 - \Delta m) C_0 = 0. \quad \text{so } m^2 - V_0^2 - \Delta m = 0$$

$$m = \frac{\Delta \pm \sqrt{\Delta^2 + 4V_0^2}}{2} = \frac{\Delta}{2} \pm \sqrt{\left(\frac{\Delta}{2}\right)^2 + V_0^2}$$

so

$$C_0(t) = A e^{i\frac{\Delta}{2}t} e^{i+\sqrt{\left(\frac{\Delta}{2}\right)^2 + V_0^2}t} + B e^{i\frac{\Delta}{2}t} e^{-i+\sqrt{\left(\frac{\Delta}{2}\right)^2 + V_0^2}t}$$

$$\text{Let } g = \sqrt{\left(\frac{\Delta}{2}\right)^2 + V_0^2}$$

~~$$C_1(t) = -i V_0 e^{i\Delta t}$$~~

$$C_1(t) = \frac{i}{V_0} e^{i\Delta t} \dot{C}_0$$

$$= \frac{i}{V_0} e^{i\frac{3\Delta t}{2}} \left( A \left( i \left( \frac{\Delta}{2} + g \right) e^{igt} + B \left( i \left( \frac{\Delta}{2} - g \right) \right) e^{-igt} \right)$$

So we want.

$$C_0(0) = 1 = A + B.$$

and

$$C_1(0) = 0 = A\left(\frac{\Delta}{2} + g\right) + B\left(\frac{\Delta}{2} - g\right)$$

$$\text{So } A = 1 - B.$$

$$\text{So } \left(\frac{\Delta}{2} + g\right) - 2gB = 0.$$

$$B = \frac{1}{2} \left(\frac{\Delta}{2g} + 1\right)$$

$$A = \frac{1}{2} \left(1 - \frac{\Delta}{2g}\right).$$

So

$$C_0(t) = e^{\frac{i\Delta t}{2}} \left( \cos \sqrt{\left(\frac{\Delta}{2}\right)^2 + v_0^2} t - i \frac{\Delta}{2g} \sin \left(\sqrt{\left(\frac{\Delta}{2}\right)^2 + v_0^2} t\right) \right)$$

$$C_1(t) = \frac{e^{\frac{i3\Delta t}{2}}}{2gV_0} \left( \left(g - \frac{\Delta}{2}\right) \left(\frac{\Delta}{2} + g\right) e^{+igt} - \left(g^2 - \frac{\Delta^2}{4}\right) e^{-igt} \right)$$

$$= \frac{e^{\frac{i3\Delta t}{2}}}{2gV_0} \left(g^2 - \frac{\Delta^2}{4}\right) \left( e^{igt} - e^{-igt} \right)$$

$$= \frac{i}{V_0 g} \left(g^2 - \frac{\Delta^2}{4}\right) e^{\frac{i3\Delta t}{2}} \sin gt = \frac{e^{\frac{i3\Delta t}{2}}}{V_0 \sqrt{\frac{\Delta^2}{4} + v_0^2}} \left(\frac{\Delta^2}{4} + v_0^2 - \frac{\Delta^2}{4}\right) \sin \left(\sqrt{\frac{\Delta^2}{4} + v_0^2} t\right)$$

$$= e^{\frac{i3\Delta t}{2}} \frac{V_0}{\sqrt{v_0^2 + \frac{\Delta^2}{4}}} \sin \sqrt{\frac{\Delta^2}{4} + v_0^2} t$$

So

$$|C_0|^2 = \cos^2 \left( \sqrt{\left(\frac{\Delta}{2}\right)^2 + V_0^2} t \right) + \frac{\Delta^2}{4g^2} \sin^2 \sqrt{\left(\frac{\Delta}{2}\right)^2 + V_0^2} t.$$

$$= \left( -1 + \frac{\Delta^2}{4g^2} \right) \sin^2 \sqrt{\left(\frac{\Delta}{2}\right)^2 + V_0^2} t + 1 =$$

$$= 1 - \frac{4V_0^2}{\Delta^2 + 4V_0^2} \sin^2 \sqrt{\left(\frac{\Delta}{2}\right)^2 + V_0^2} t.$$

$$|C_1|^2 = \frac{4V_0^2}{\Delta^2 + 4V_0^2} \sin^2 \sqrt{\left(\frac{\Delta}{2}\right)^2 + V_0^2} t.$$

with  $|C_0|^2 + |C_1|^2 = 1$ .

In limit that  $V_0 \ll \Delta$ .

$$|C_1|^2 \approx \frac{4V_0^2}{\Delta^2} \left( 1 - \frac{4V_0^2}{\Delta^2} \right) \left( \sin^2 \frac{\Delta t}{2} \left( 1 + \frac{2V_0^2}{\Delta^2} \right) \right)$$

$$\approx \frac{4V_0^2}{\Delta^2} \sin^2 \frac{\Delta t}{2} + O(V_0^4).$$

From before we had.

$$|C_1|^2 = \frac{V_0^2}{\Delta^2} 2 \left( 1 - \cos \Delta t \right) = \frac{4V_0^2}{\Delta^2} \sin^2 \frac{\Delta t}{2} \quad \checkmark$$

checks out!