

Problem I

Notice that P, C commute with c -numbers.
I'll also assume $P^2 = C^2 = 1, P = P^\dagger, C = C^\dagger$.

(1) Plugging (3) into (4) at $t=0$

$$\begin{aligned} \text{LHS} &= P \Psi(\vec{x}, 0) P = P \int d\vec{p} \sum_s (a(p,s) u(p,s) e^{-i\vec{p}\cdot\vec{x}} + b^\dagger(p,s) v(p,s) e^{i\vec{p}\cdot\vec{x}}) P \\ &= \int d\vec{p} \sum_s (P a(p,s) P u(p,s) e^{-i\vec{p}\cdot\vec{x}} + P b^\dagger(p,s) P v(p,s) e^{i\vec{p}\cdot\vec{x}}) \\ &= \text{RHS} = \gamma^0 \Psi(-\vec{x}, 0) = \gamma^0 \int d\vec{p} \sum_s (a(p,s) u(p,s) e^{i\vec{p}\cdot\vec{x}} + b^\dagger(p,s) v(p,s) e^{-i\vec{p}\cdot\vec{x}}) \\ &\stackrel{\text{use (1)}}{=} \int d\vec{p} \sum_s (a(p,s) u(-p,s) e^{i\vec{p}\cdot\vec{x}} - b^\dagger(p,s) v(-p,s) e^{-i\vec{p}\cdot\vec{x}}) \\ &\stackrel{(p \rightarrow -p)}{\int d\vec{p} \rightarrow \int d\vec{p}} = \int d\vec{p} \sum_s (a(-p,s) u(p,s) e^{-i\vec{p}\cdot\vec{x}} - b^\dagger(p,s) v(-p,s) e^{i\vec{p}\cdot\vec{x}}) \end{aligned}$$

Now I can match the coefficients of the boxed equations above, as they hold for all \vec{x} and $e^{-i\vec{p}\cdot\vec{x}}$ are lin. indep. (except, of course $e^{-i\vec{p}\cdot\vec{x}}$ is $e^{i\vec{p}\cdot\vec{x}}$ when $\vec{p} \rightarrow -\vec{p}$, but $u(p,s)$ and $v(p,s)$ are lin indep.). Alternately I could Fourier transform to justify matching these coefficients.

Matching:

$$\boxed{P a(\vec{p}, s) P = a(-\vec{p}, s)} \quad \text{and} \quad \boxed{P b^\dagger(\vec{p}, s) P = -b^\dagger(-\vec{p}, s)}$$

taking the conj transpose, $P = P^\dagger$
so $\boxed{P b(\vec{p}, s) P = -b(-\vec{p}, s)}$

(2) Plugging (3) into (5) at $t=0$

$$\begin{aligned} \text{LHS} &= C \Psi(\vec{x}, 0) C = \int d\vec{p} \sum_s C a(p,s) C u(p,s) e^{-i\vec{p}\cdot\vec{x}} + C b^\dagger(p,s) C v(p,s) e^{i\vec{p}\cdot\vec{x}} \\ &= \text{RHS} = i \gamma^0 \gamma^2 \Psi^\dagger(\vec{x}, 0) = i \gamma^0 \gamma^2 (\Psi^\dagger \gamma^0)^T \\ &= i \gamma^0 \gamma^2 \gamma^0 (\Psi^\dagger)^T = \int d\vec{p} \sum_s (a^\dagger(p,s) \gamma^0 \gamma^2 \gamma^0 (u^\dagger)_{(p,s)}^T e^{+i\vec{p}\cdot\vec{x}} + b(p,s) \gamma^0 \gamma^2 \gamma^0 (v^\dagger)_{(p,s)}^T e^{-i\vec{p}\cdot\vec{x}}) \\ &= \int d\vec{p} \sum_s (a^\dagger(p,s) \gamma^0 \gamma^2 \frac{I}{u(p,s)} e^{+i\vec{p}\cdot\vec{x}} + b(p,s) \gamma^0 \gamma^2 \frac{I}{v(p,s)} e^{-i\vec{p}\cdot\vec{x}}) \\ &= \int d\vec{p} \sum_s (a^\dagger(p,s) v(p,s) e^{+i\vec{p}\cdot\vec{x}} + b(p,s) u(p,s) e^{-i\vec{p}\cdot\vec{x}}) \end{aligned}$$

Matching: $C a(p,s) C = b(p,s)$ and $C b^\dagger(p,s) C = a^\dagger(p,s) \Rightarrow C b(p,s) C = a(p,s)$

(3) I'll use the identity (from, e.g. Jackson)

$$Y_m^l(-\vec{p}) = (-1)^l Y_m^l(\vec{p})$$

and I'll use $P|0\rangle = |0\rangle$, parity invariance of the vacuum,

$$P|l, m; 0, 0\rangle = \int d^3\vec{p} [P a^\dagger(\vec{p}, +) P P b^\dagger(-\vec{p}, -) P - P a^\dagger(\vec{p}, -) P P b^\dagger(-\vec{p}, +)] \\ \times Y_m^l(\vec{p}) f(|\vec{p}|) P|0\rangle$$

where I've inserted $PP=1$ and used $P Y_m^l(\vec{p}) P = Y_m^l(\vec{p})$ ^{C-number}
 Now I'll use the results of part (1):

$$P|l, m; 0, 0\rangle = \int d^3\vec{p} [a^\dagger(\vec{p}, +) (-b^\dagger(\vec{p}, -)) - (a^\dagger(\vec{p}, -)) (-b^\dagger(\vec{p}, +))] \\ \times Y_m^l(\vec{p}) f(|\vec{p}|) |0\rangle \\ (\vec{p} \rightarrow -\vec{p}) \\ = - \int d^3\vec{p} [a^\dagger(\vec{p}, +) b^\dagger(-\vec{p}, -) - a^\dagger(\vec{p}, -) b^\dagger(-\vec{p}, +)] Y_m^l(-\vec{p}) f(|-\vec{p}|) |0\rangle \\ = -(-1)^l \int d^3\vec{p} [a^\dagger(\vec{p}, +) b^\dagger(-\vec{p}, -) - a^\dagger(\vec{p}, -) b^\dagger(-\vec{p}, +)] Y_m^l(\vec{p}) f(|\vec{p}|) |0\rangle \\ = \boxed{(-1)^l |l, m; 0, 0\rangle}$$

(4) $C|l, m; 0, 0\rangle = \int d^3\vec{p} [C a^\dagger(\vec{p}, +) C C b^\dagger(-\vec{p}, -) C - C a^\dagger(\vec{p}, -) C C b^\dagger(-\vec{p}, +)] Y_m^l(\vec{p}) f(|\vec{p}|) |0\rangle$ ^{use $C|0\rangle = |0\rangle$}

$$= \int d^3\vec{p} [b^\dagger(\vec{p}, +) a^\dagger(-\vec{p}, -) - b^\dagger(\vec{p}, -) a^\dagger(-\vec{p}, +)] Y_m^l(\vec{p}) f(|\vec{p}|) |0\rangle$$

(use $a^\dagger b^\dagger = -b^\dagger a^\dagger$)

$$= - \int d^3\vec{p} [a^\dagger(-\vec{p}, -) b^\dagger(\vec{p}, +) - a^\dagger(-\vec{p}, +) b^\dagger(\vec{p}, -)] Y_m^l(\vec{p}) f(|\vec{p}|) |0\rangle$$

$$= \int d^3\vec{p} [a^\dagger(-\vec{p}, +) b^\dagger(\vec{p}, -) - a^\dagger(-\vec{p}, -) b^\dagger(\vec{p}, +)] Y_m^l(\vec{p}) f(|\vec{p}|) |0\rangle$$

($\vec{p} \rightarrow -\vec{p}$)

$$= \int d^3\vec{p} [a^\dagger(\vec{p}, +) b^\dagger(-\vec{p}, -) - a^\dagger(\vec{p}, -) b^\dagger(-\vec{p}, +)] Y_m^l(-\vec{p}) f(|-\vec{p}|) |0\rangle$$

$$= (-1)^l \int d^3\vec{p} [a^\dagger(\vec{p}, +) b^\dagger(-\vec{p}, -) - a^\dagger(\vec{p}, -) b^\dagger(-\vec{p}, +)] Y_m^l(\vec{p}) f(|\vec{p}|) |0\rangle$$

$$= \boxed{(-1)^l |l, m; 0, 0\rangle}$$

$$\begin{aligned}
 (5) \quad P |l, m, j, 1\rangle &= \int d^3\vec{p} [P a^\dagger(\vec{p}, +) P P b^\dagger(-\vec{p}, +) P] Y_m^l(\vec{p}) f(|\vec{p}|) |p\rangle \\
 &= -\int d^3\vec{p} a^\dagger(-\vec{p}, +) b^\dagger(\vec{p}, +) Y_m^l(\vec{p}) f(|\vec{p}|) |0\rangle \\
 (\vec{p} \rightarrow -\vec{p}) &= -\int d^3\vec{p} a^\dagger(\vec{p}, +) b^\dagger(-\vec{p}, +) Y_m^l(-\vec{p}) f(|\vec{p}|) |0\rangle \\
 &= -(-1)^l |l, m, j, 1\rangle
 \end{aligned}$$

$$\begin{aligned}
 (6) \quad C |l, m, j, 1\rangle &= \int d^3\vec{p} [C a^\dagger(\vec{p}, +) C C b^\dagger(\vec{p}, +) C] Y_m^l(\vec{p}) f(|\vec{p}|) |0\rangle \\
 &= \int d^3\vec{p} [b^\dagger(\vec{p}, +) a^\dagger(-\vec{p}, +)] Y_m^l(\vec{p}) f(|\vec{p}|) |0\rangle \\
 (a^\dagger b^\dagger = -b^\dagger a^\dagger) &= -\int d^3\vec{p} [a^\dagger(-\vec{p}, +) b^\dagger(\vec{p}, +)] Y_m^l(\vec{p}) f(|\vec{p}|) |0\rangle \\
 (\vec{p} \rightarrow -\vec{p}) &= -\int d^3\vec{p} [a^\dagger(\vec{p}, +) b^\dagger(-\vec{p}, +)] (-1)^l Y_m^l(\vec{p}) f(|\vec{p}|) |0\rangle \\
 &= \boxed{-(-1)^l |l, m, j, 1\rangle}
 \end{aligned}$$

Problem II: Use $P = (-1)^{L+1}$, $C = (-1)^{L+S}$ for fermion pair bound states

(1) $L=0$ so $P = (-1)^{L+1} = -1$ so these are pseudoscalars

(2) I'll guess:

$$|K_1\rangle = |K^0\rangle - |\bar{K}^0\rangle, \quad |K_2\rangle = |K^0\rangle + |\bar{K}^0\rangle$$

Now I'll check this.

First notice $CP |K^0\rangle = (-1)^{L+S} (-1)^{L+1} |\bar{K}^0\rangle = -|\bar{K}^0\rangle$

$$CP |\bar{K}^0\rangle = (-1)^{2L+S+1} |K^0\rangle = -|K^0\rangle$$

And so

$$CP |K_1\rangle = CP (|K^0\rangle - |\bar{K}^0\rangle) = -|\bar{K}^0\rangle + |K^0\rangle = |K_1\rangle$$

$$CP |K_2\rangle = CP (|K^0\rangle + |\bar{K}^0\rangle) = -|\bar{K}^0\rangle - |K^0\rangle = -|K_2\rangle$$

So $|K_1\rangle$ and $|K_2\rangle$ are CP eigenstates with eigenvalues 1 and -1 respectively as desired.

(3) π^0 is a 2-fermion bound state, so $P = (-1)^{L+1} = -1$, $C = (-1)^{L+S} = 1$.

$\overline{\pi^0} = \bar{u}\bar{u} - \bar{d}\bar{d} = \bar{u}u - \bar{d}d = \pi^0$, so π^0 is its own antiparticle.

Let $a^\dagger(\vec{p})$ create a π^0 with momentum \vec{p} . By above

$$P a^\dagger(\vec{p}) |0\rangle = -a^\dagger(\vec{p}) |0\rangle \quad \text{because } P = -1$$

however

$$P a^\dagger(\vec{p}) |0\rangle = P a^\dagger(\vec{p}) P P |0\rangle = P a^\dagger(\vec{p}) P |0\rangle$$

And so, taking from the lecture of Sept 10, 1999

$$P a^\dagger(\vec{p}) P = \eta_p a^\dagger(-\vec{p})$$

We find $\eta_p = -1$, so

$$P a^\dagger(\vec{p}) P = -a^\dagger(-\vec{p})$$

Likewise, as $\overline{\pi^0} = \pi^0$,

$$C a^\dagger(\vec{p}) C = a^\dagger(\vec{p})$$

Now to create a state of $2\pi^0$ with no angular momentum:

$$\int d\vec{p} a^\dagger(\vec{p}) a^\dagger(-\vec{p}) \frac{1}{\sqrt{2}} f(|\vec{p}|) |0\rangle$$

$$\begin{aligned} CP \left\{ \int d\vec{p} a^\dagger(\vec{p}) a^\dagger(-\vec{p}) f(|\vec{p}|) |0\rangle \right\} &= \int d\vec{p} (CP a^\dagger(\vec{p}) PC) (CP a^\dagger(-\vec{p}) PC) f(|\vec{p}|) CP |0\rangle \\ &= \int d\vec{p} (-a^\dagger(\vec{p})) (-a^\dagger(-\vec{p})) f(|\vec{p}|) |0\rangle \\ &= \int d\vec{p} a^\dagger(\vec{p}) a^\dagger(-\vec{p}) f(|\vec{p}|) |0\rangle \end{aligned}$$

which is just the original state. So this bound state has $CP = 1$.

(4) $CP a^\dagger(\vec{p}_1) a^\dagger(\vec{p}_2) a^\dagger(\vec{p}_3) f |0\rangle = (-1)^3 a^\dagger(\vec{p}_1) a^\dagger(\vec{p}_2) a^\dagger(\vec{p}_3) f |0\rangle$

Similarly to above, so this state (this is the 0 ang mom state) will have $CP = -1$, like K_2 .

Therefore

$$K_2 \rightarrow \pi^0 \pi^0 \pi^0 \text{ is allowed.}$$